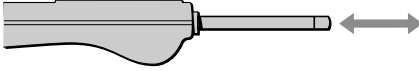


# ST1000+ and ST2000+ Quick Reference Guide

## Basic operation

Auto mode

Extending/retracting the pushrod



Use any of these keys to extend or retract the pushrod

-1

+1

or

-10

+10

Making course changes

Course changes to port

←

-1 1° +1

-10 10° +10

→

Course changes to starboard

Returning to previous locked heading

1 sec then again to accept heading

Returning to Standby (Disengaging the autopilot)

C 306°

Entering Auto mode (Engaging the autopilot)

A 235°

WindTrim mode

Entering WindTrim mode

and

U 306°

Press **standby** or **auto** to exit WindTrim mode.

Track mode

Entering Track mode (from Auto or Wind Vane mode)

-10 and +10 to enter Track mode

t 058°  
W.Pt

→

t 058°  
W.Pt

then -10 and +10 to accept new heading

Press **standby** or **auto** to exit.

t 058°

Using AutoTrack

AutoTrack to port (100°)

←

-1 +1

-10 +10

→

AutoTrack to starboard (100°)

Autopilot displays

Displaying navigation data (from Auto or Standby modes)

-1 and +10

t 058°

135°  
W.Pt

r 023°  
nm

058°  
W.Pt

Press -1 and +10 together to exit.

Switching lighting on/off (from Standby mode only)

Press -1 and +1 to switch between:

L 1

ON

L 0

OFF

Wait 10 sec to return to previous mode.

Switching AutoSeastate on/off (from Auto/Track/WindTrim modes)

Press -1 and +1 to switch between:

A 258°

ON

A 258°

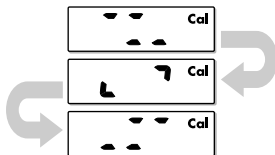
OFF

D3364-2

# ST1000+ and ST2000+ Quick Reference Guide

## Compass calibration

### 1 Enter compass calibration

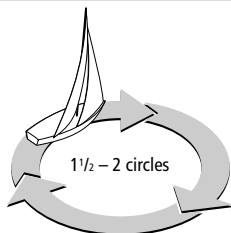


Start turning boat  
(see 2 below)

### 2 Turn boat in slow circles

Turn the boat in slow circles so:

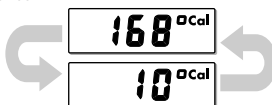
- boat's speed stays below 2 knots
- each circle takes at least 3 minutes



### 3 Autopilot displays amount of deviation detected

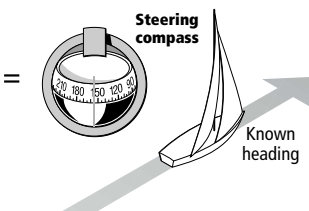
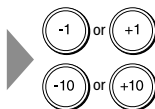
Keep turning the boat until the display alternates between:

- autopilot heading
- deviation detected



### 4 Align the autopilot heading

Adjust the autopilot heading to match the boat's steering compass



### 5 Save changes



- To:
- save deviation correction
  - save heading alignment
  - return to STANDBY mode



- To:
- quit compass calibration without saving